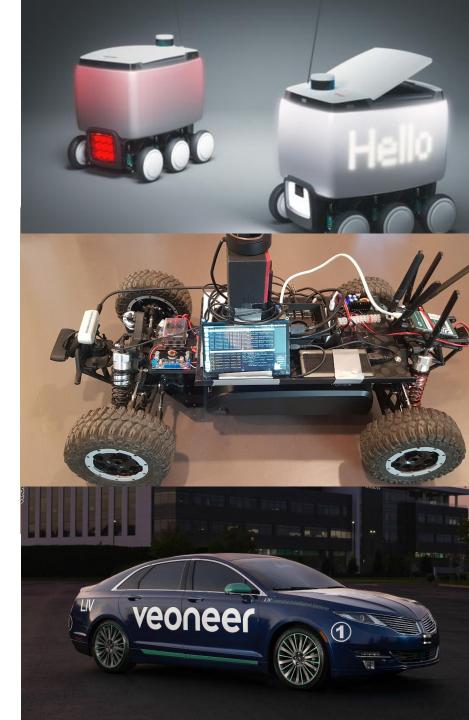
3GPP Delivery robot project

Stig Persson

Enabling novel digital-twin applications for autonomous and connected vehicles

- Establishment within Kista's Automotive Trial Site of the world's first "living lab" for testing and demonstrating connected sensors
 - Supporting applied research explorations
 - Enabling novel and compelling demonstrators with partners
- Exploring how real-time "digital twins" and HD mapping can increase safety, reduce costs and enable new business models
 - Control types: ADAS, Remote control/driving, AD
 - Service types: People, Goods
 - Settings: Open roads, Dedicated areas (bike lane, sidewalk)
- Number of exploratory projects/cooperations for "bootstrapping" the Trial Site with real world data and services



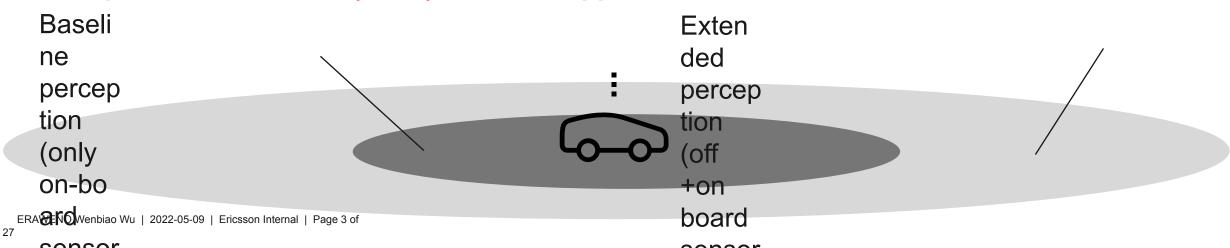
The underlying vision:

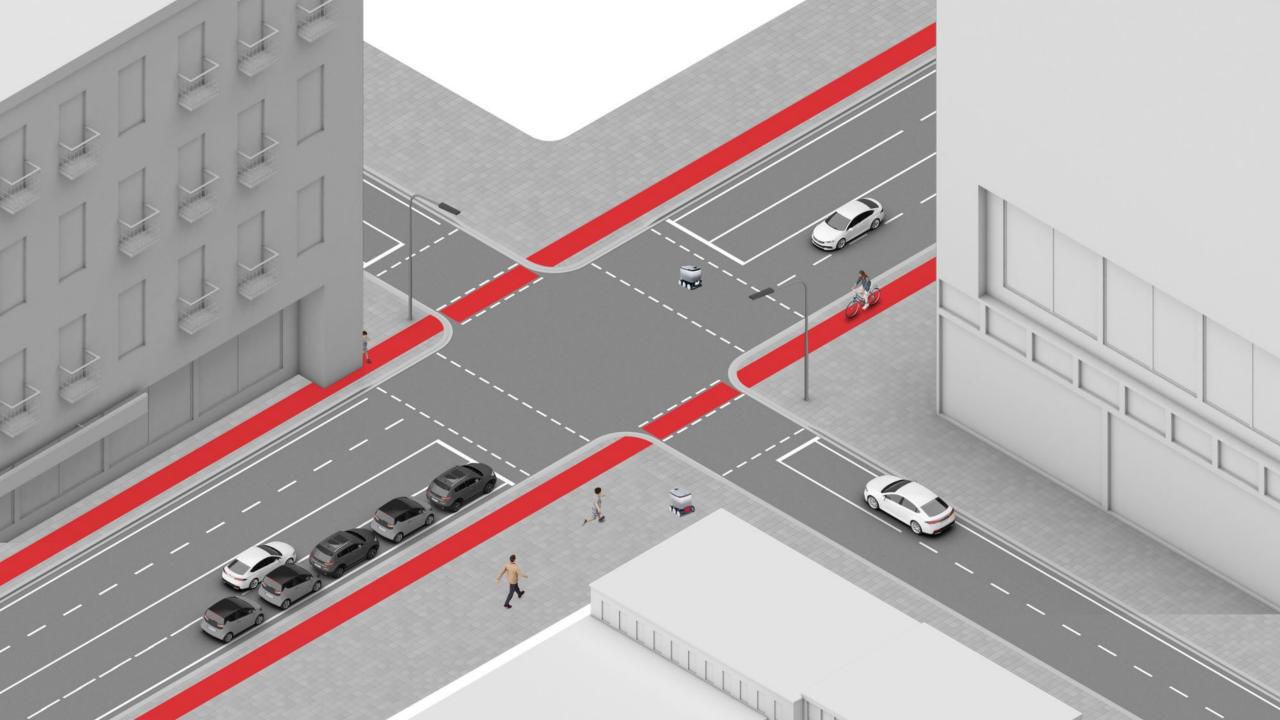
"Off-board sensors will be an essential technology for (semi)autonomous vehicles driving"

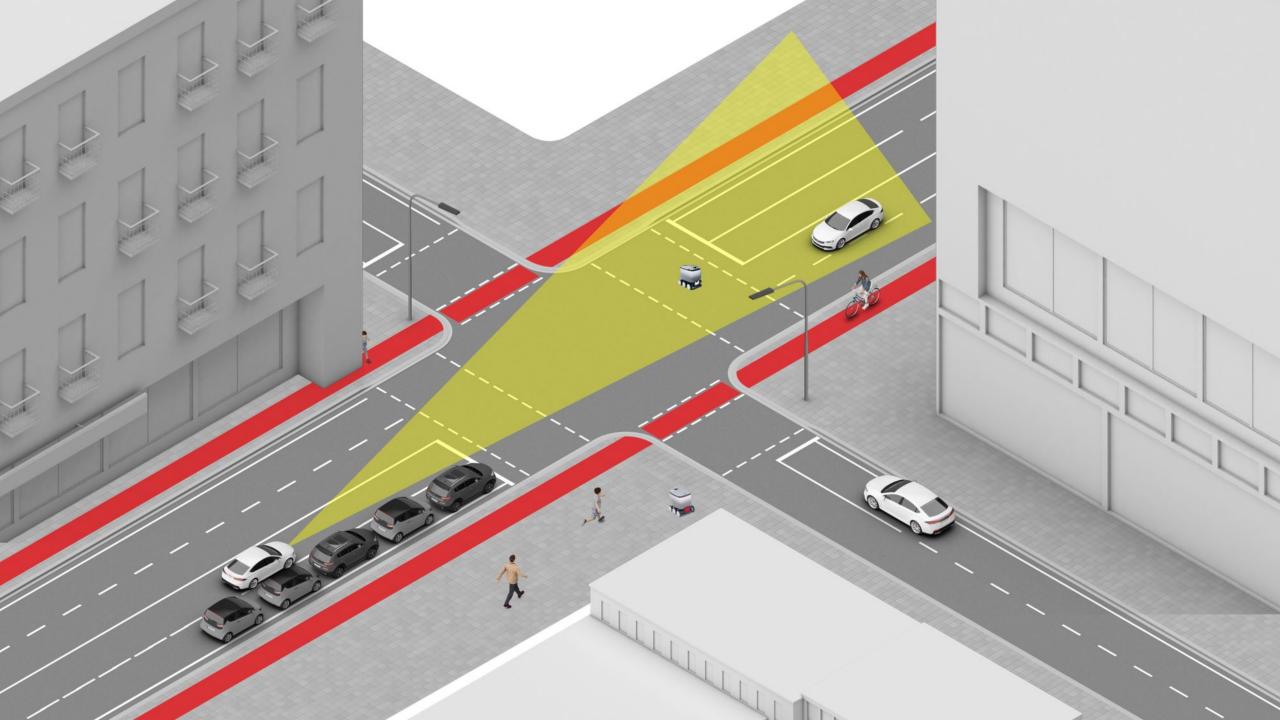
Potential gains:

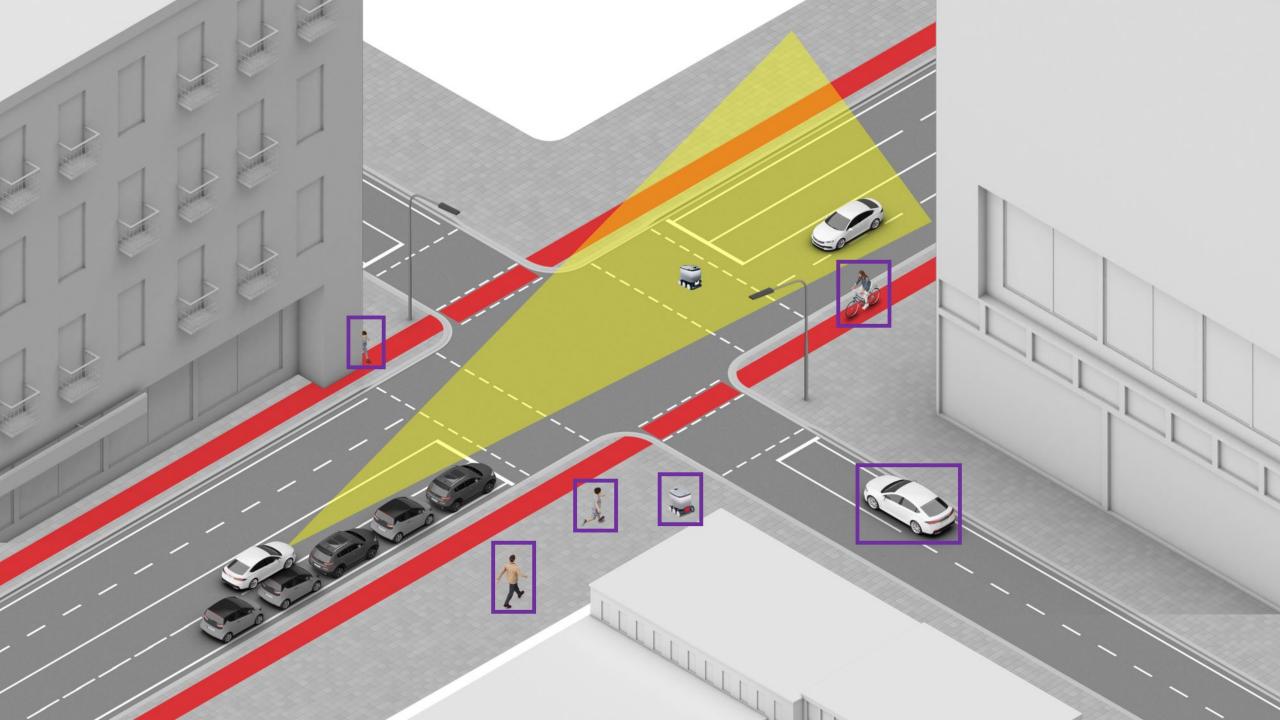
- Complementary Fields of View extend vehicle performance
- Cross-sensors validation for safety, and fault detection
- Reduction of device cost and complexity without lowing system reliability

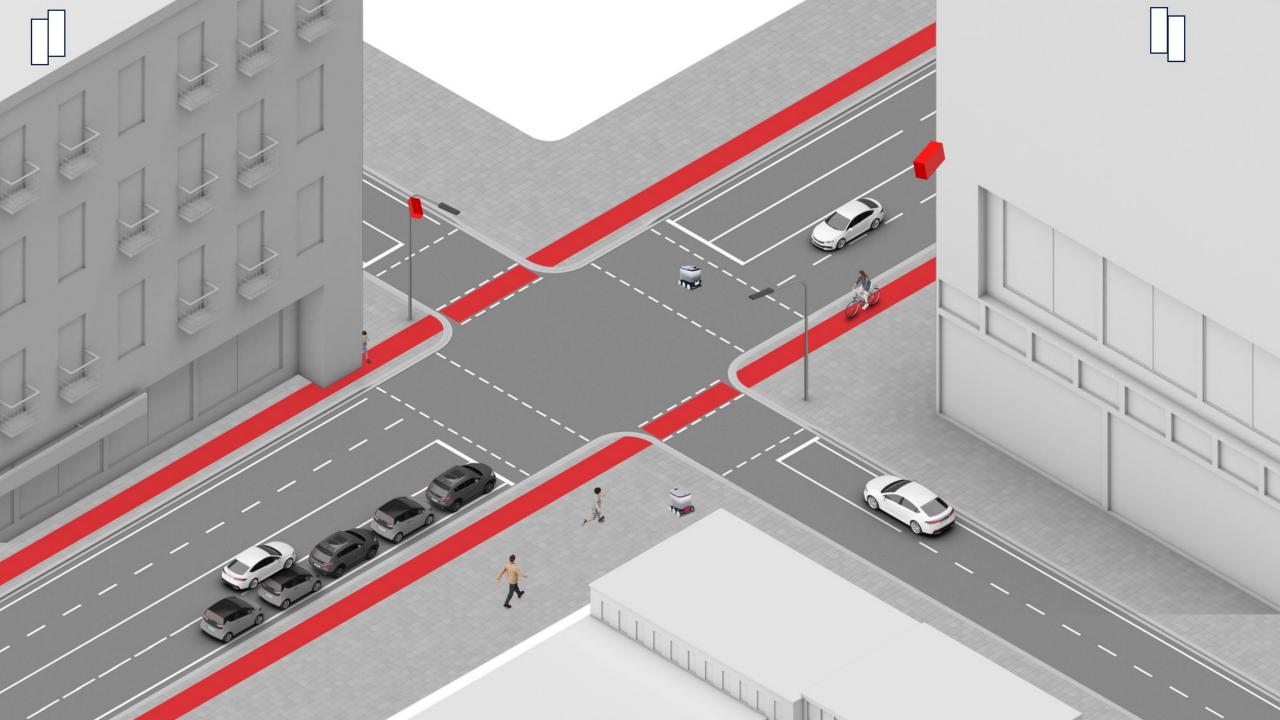
"Perception as a Service" (PaaS) business opportunities

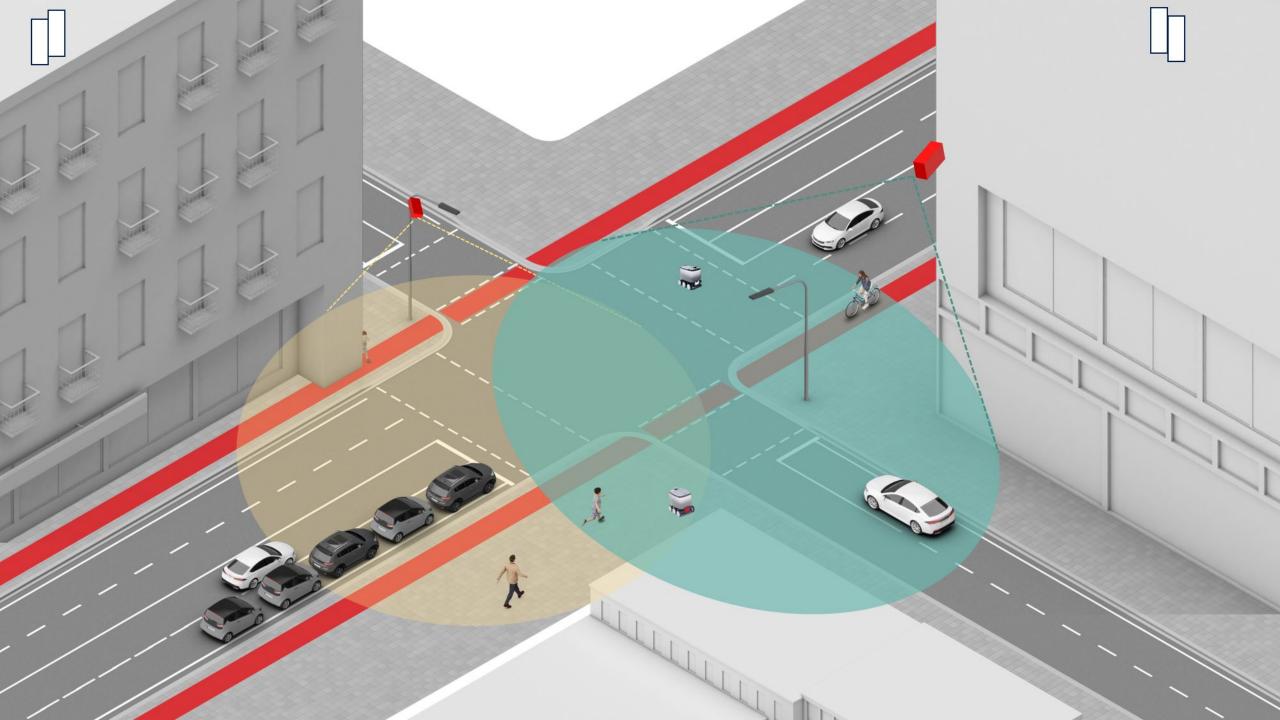


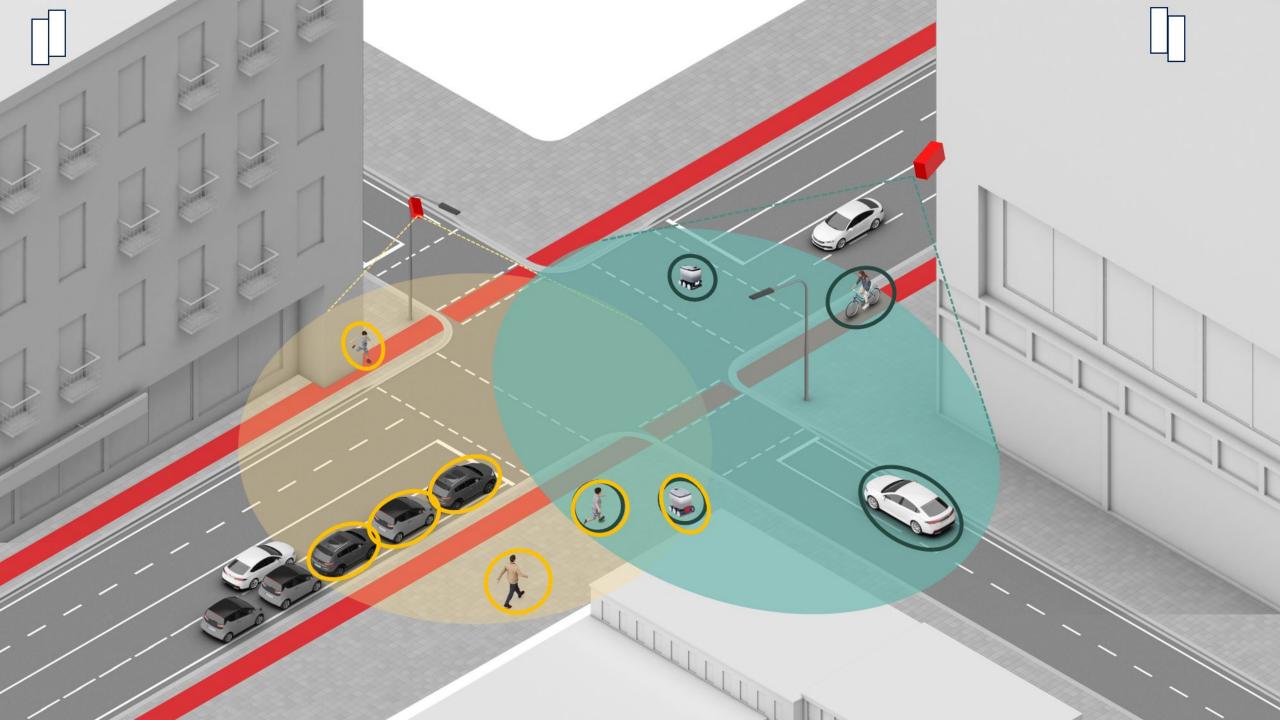


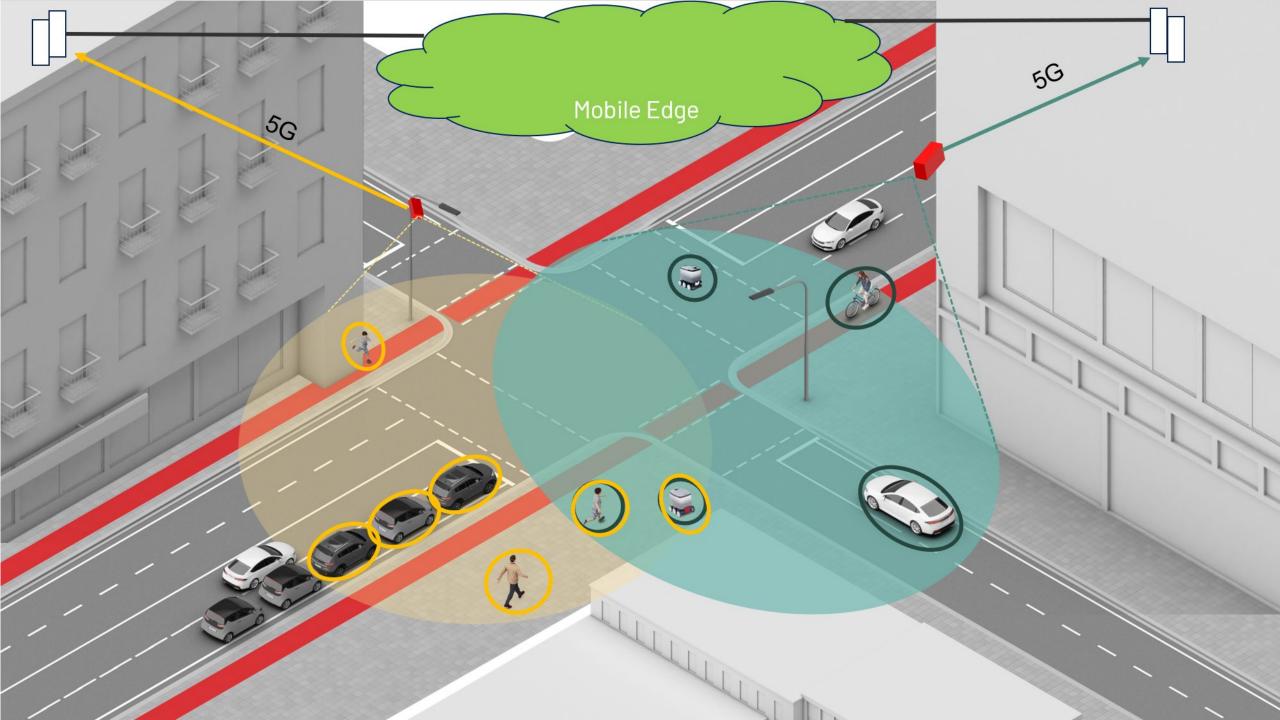


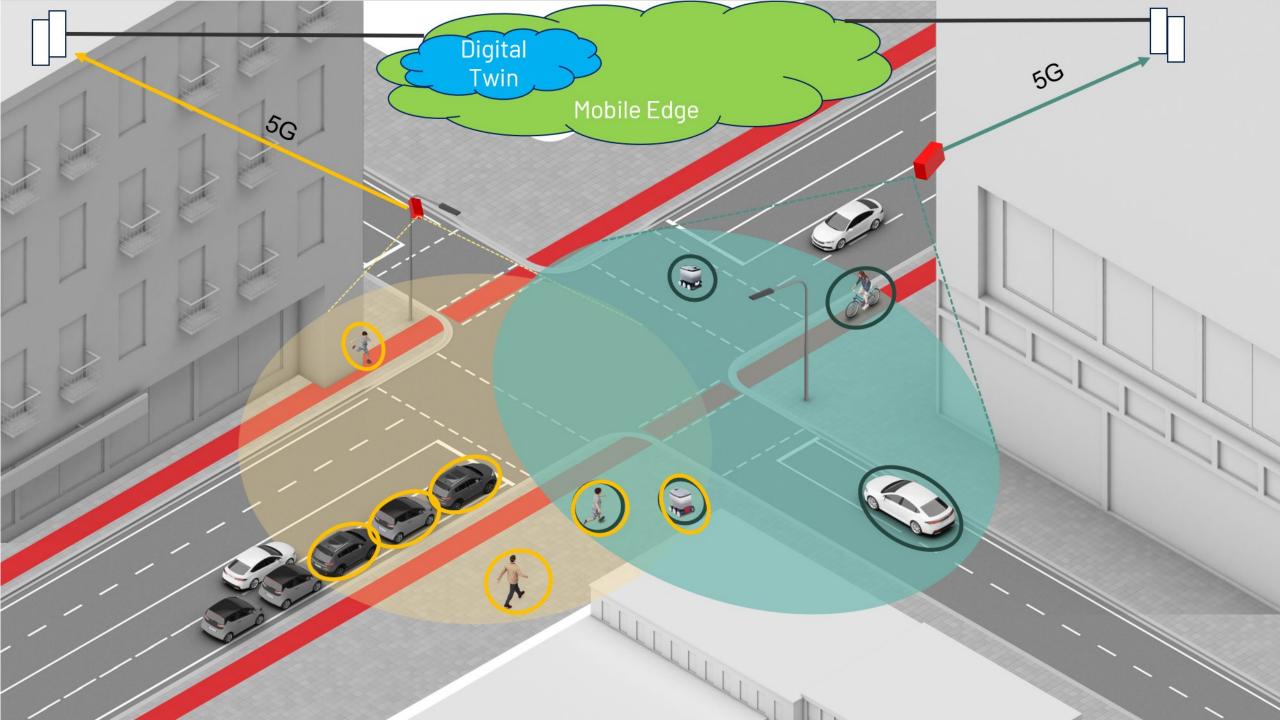


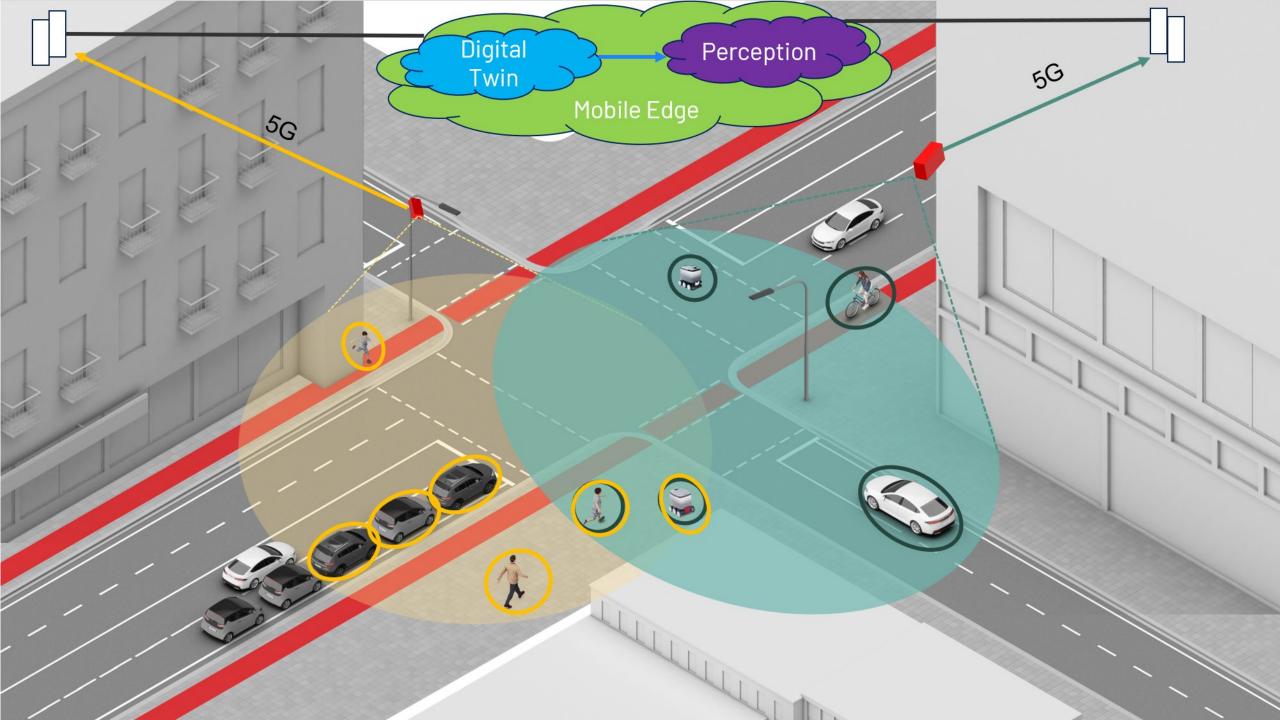


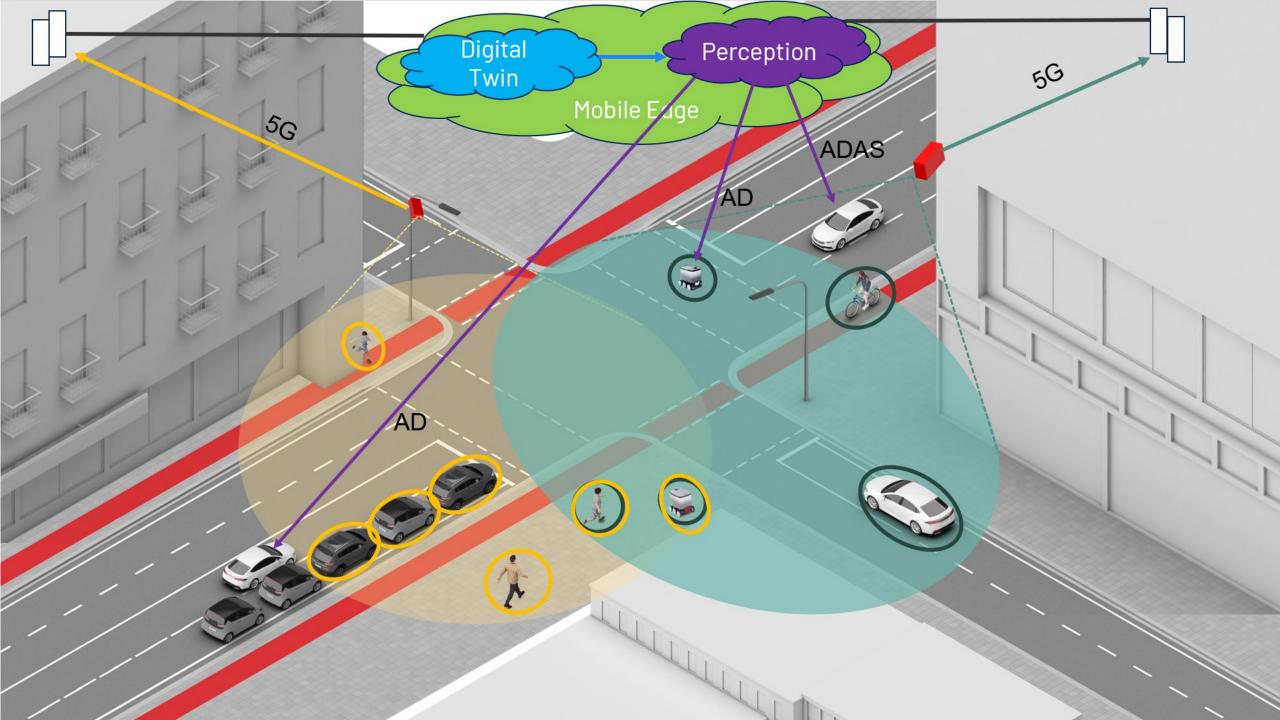












Sensoring Network In Kista

Built For 3GPP Last Mile Delivery Project

Last mile delivery use

Studi



views UC locations



House

UC2

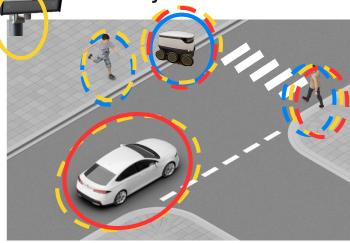
House

UC3

UC1

Sensor fusion

- We have several sensors streaming detected objects on individual MQTT topics
 - First step is to combine several sensor streams into one topic
- Some sensors will have overlapping coverage which will result in some objects detected twice
 - Step two is to fuse objects detected several times into one object









- <u>https://ericsson-my.sharepoint.com/:f:/p/pietro_lungaro/Eu8Leeh0iHdPh8KF9u6OG3wB35oK6kD</u> E009T2K-0c_aZGQ?e=7BmVta
- <u>Video2</u>

